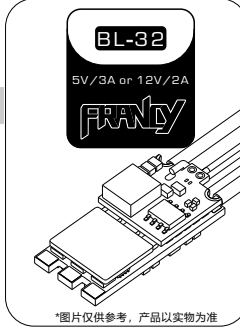




感谢您购买本产品！本产品功率强大，错误的使用可能导致人身伤害和设备损坏，强烈建议您在设备使用前仔细阅读本说明书并保存，严格遵守规定的操作程序。我们不承担因使用本产品或擅自对产品进行改造所引起的一切责任，包括但不限于对附带损失或间接损失的赔偿责任。我们有权在不通知的情况下变更产品的设计、外观、性能及使用要求。

## 01 主要特性

- ARM 32-bit Cortex 核心MCU，工作频率高达48MHz；
- BLHeli-32 固件，超快响应速度，卓越的性能；
- 电调上电自动检测油门信号，支持普通PWM油门模式（1-2ms）的脉宽输入、Oneshot125（125-250us）、Oneshot42（41.7-83.3us）和 Multishot（5-25us）；
- 支持所有Dshot数字信号；
- Damped light再生制动，使得效率更高，油门从大到小变化时电机减速响应更加迅速，稳定性和灵活性显著加强；
- 体积小、重量轻；支持更高KV电机和更大功率负载；
- 模块化BEC，BEC输出可供电接收机、舵机等外部设备，使得电调应用更加广泛；
- BEC 输出5V/3A；12V/2A可调节，应用更灵活；
- 铝合金散热器，有效减缓温升(50A/40A)；支持RGB三色灯设置(30A/20A),让飞行更绚丽多彩。



\*图片仅供参考，产品以实物为准

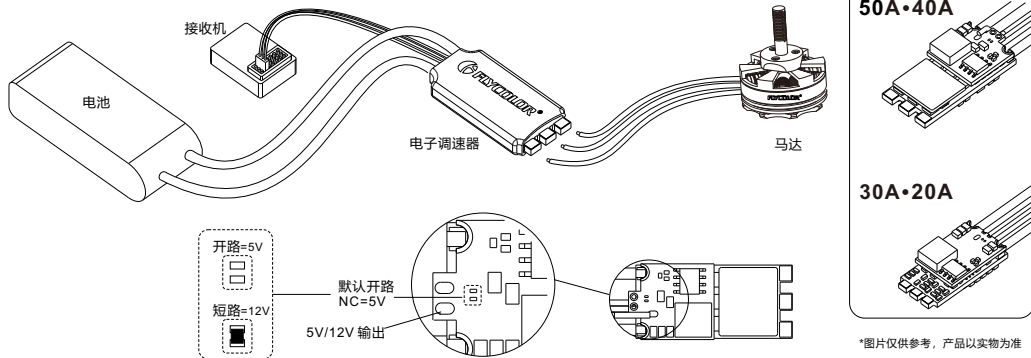
## 02 产品规格

型号	持续电流 (散热良好)	瞬间电流 (10S 散热良好)	BEC; 锂电池节数 5V/3A ; (3-6S) 12V/2A ; (4-6S)	重量 (供参考,包含线材)	尺寸 (供参考)	LED设置
Francy-20A	20A	25A	5V/3A ; (3-6S) 12V/2A ; (4-6S)	12.5g	29x14x9mm	RGB LED
Francy-30A	30A	35A	5V/3A ; (3-6S) 12V/2A ; (4-6S)	12.5g	29x14x9mm	RGB LED
Francy-40A	40A	50A	5V/3A ; (3-6S) 12V/2A ; (4-6S)	16.5g	33x16x10mm	红色LED
Francy-50A	50A	60A	5V/3A ; (3-6S) 12V/2A ; (4-6S)	16.5g	33x16x10mm	红色LED

- 1)40A/50A 固件:Flycolor\_X\_Cross\_BL\_32; 2)20A/30 固件:Flycolor\_X\_Cross\_BL\_32\_35A
- 当选择5V/3A BEC输出时，工作电压支持3-6S锂电池；当选择12V/2A BEC输出时，工作电压支持4-6S锂电池。

## 03 连线示意图

\*为避免短路和漏电，请确保连接处绝缘良好



\*图片仅供参考，产品以实物为准

## 04 编程参数值

以下的参数需要通过BLHeliSuite32调参软件设置

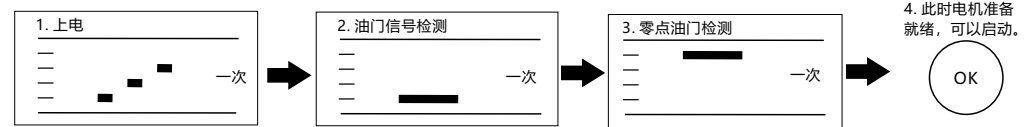
- 启动功率 (Rampup power) :**  
启动功率可以设置为从3%-150%的相对值。这是在启动和提高转速时允许最大功率。对于低转速，为了便于低反电动势电压检测，最大功率是被限制的。启动功率也会影响双向操作，参数是用来限制在更改转向时的功率。在启动过程中，实际功率取决于油门输入，可低于设定的最大启动功率，但最低是设定的四分之一。
- 电机进角 (Motor timing) :**  
电机进角可以设置为1°-31°，通常设置中等数值进角即适用于大部分电机，但如果电机运转不顺畅时，可以尝试改变进角。对于一些高感电机，其换向退磁时间较长，尤其在低速运转的时候，电机会在油门快速增加的情况下下停转或者不顺畅。将进角调高会有助于改善这个现象，因为高进角允许更长的换向退磁时间。
- PWM频率 (PWM frequency) :** 电机PWM频率可设置为16KHz-48KHz，更高PWM频率使电机运行更顺畅，频率可设定有可能导致油门轻微移动时造成大的波动。
- Demag补偿 (Demag compensation) :**  
Demag 补偿是防止电机由于换向引起停转的一个功能，典型的现象是在快速增加油门时电机停转或不顺畅，尤其在低转速运行时。如前面所述，设置高进角可以帮助改善，但有可能降低效率。一般情况下，Demag补偿参数的值越高，保护越好。如果补偿值设置得太高，最大功率将有所降低。

### 5. 最大加速度 (Maximum Acceleration) :

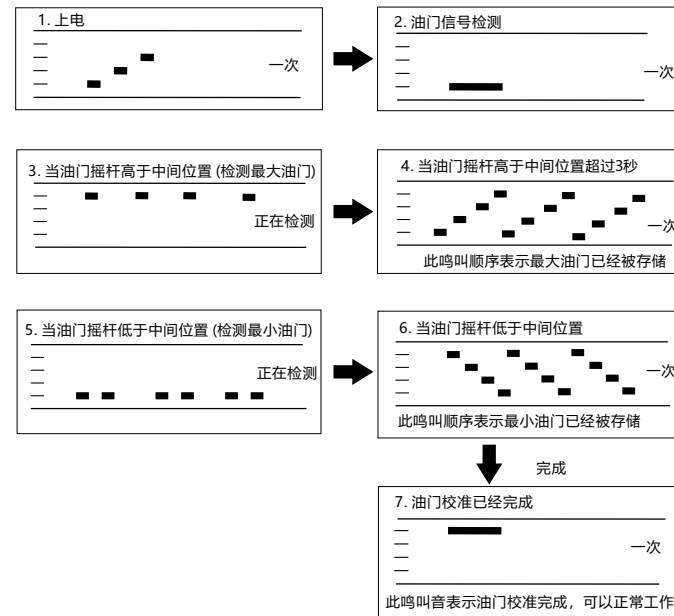
最大加速度可以设置在0.1% / ms-25.5% / ms之间，也可以设置为最大值，在这种情况下加速度不受限制。限制加速度的主要目的是避免在加速不一致造成失步的情况。例如：当设置为10% / ms时，这意味着对电动机施加的功率不允许每毫秒增加10%以上。

- 电机转向 (Motor Direction) :** 电机转向可以设置为正转/反转/双向3D/双向3D反转/双向soft/双向soft反转。在双向模式下，油门中点为零点，中点以上为正转,中点以下为反转；当选择双向操作时，不可油门校准。
- 鸣叫声强度 (Startup Beep Volume) :** 设置正常上电时鸣叫声强度。
- 警报音强度 (Beacon/Signal Volume) :**  
设置警报音响起时的强度。如果油门信号在零点位置的时间超过一个设定的时间，电调将开始报警。请注意如果设置一个高的警报强度将会导致电机或电调发热。
- 警报音延迟 (Beacon delay) :** 设置报警音开始之前的延时。
- 启用油门校准 (Throttle Cal Enable) :** 如果禁用，将不能油门校准。
- 最小油门，最大油门和中心油门 (Min throttle, max throttle and center throttle) :**  
设置电调的油门范围；中点油门只用于双向操作；设置值正常的为900us 到 2100us的输入信号。对于其他输入信号，该值必须按比例设置。对于Dshot输入信号，这些设置无效。
- 温度保护 (Thermal protection) :**  
可以启用或禁用。温度保护阈值可以设置，当温度高于阈值时,电机功率降低；当温度高于阈值15°C电机功率降低到25%；电机功率不会低于25%。
- 低转速功率保护 (Low RPM power protect) :**  
低转速功率限制可以启用或禁用。禁用它可以保证低KV电机在低电压运行时实现全功率，然而禁用它将增加同步丢失的风险，伴随着电机或ESC发热的可能性。
- 低压保护 (Low Voltage Protection) :**  
低压保护可以设置2.5V/节-4.0V/节锂电池，或者可以禁用。当启用时，如果电池电压低于设定阈值将限制电机的功率。此功能主要用于固定翼飞机。
- 停车制动 (Brake on stop) :**可以启用或禁用制动。当设置启用时，在通电状态，油门在零点位置电机将会有拖刹，阻止电机转动。如果油门没有零点，此项无效。
- LED控制 (LED control) :** 对于支持的ESC，可以控制发光二极管(如果ESC支持)。
- 无 Damped 模式 (Non Damped Mode) :** OFF- 有Damped 现象为刹车；ON- 无Damped 现象为无刹车。
- 音乐设置 (Music Note Config) :** 可以设置个性化音乐。
- 正弦调制方式 (Sine Modulation Mode) :** 可以启用或禁用。正弦调制模式可以使运行效率提高百分之几，运行更流畅。
- 自动遥测 (Auto Telemetry) :** 当启用自动遥测时，ESC将以32ms的间隔自主地输出遥测，而不管是否存在来自输入信号的遥测请求。
- 堵转保护 (Stall Protection) :** 当电机尝试启动未能成功，将停止启动。Normal-保护，Relaxed-无保护。

## 05 正常工作及提示音



## 06 油门校准



- 1.使用飞控调参软件校准油门将更简便;
- 2.首次使用无刷电调或更换遥控设备后需要进行油门行程校准;
- 3.当输入信号为Dshot模式时，将不再需要校准油门，请忽略此步骤。

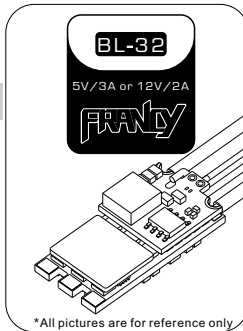
图示举例:



Thank you for using our product. Any improper operation may cause personal injury or damage to the product and related equipments. This high power system for RC model can be dangerous, we strongly recommend reading the user manual carefully and completely. We will not assume any responsibility for any losses caused by unauthorized modifications to our product. We have the right to change the design, appearance, performance and usage requirements of the product unannounced.

## 01 Main features

- ARM 32-bit Cortex MCU, frequency up to 48 MHz.
- BLHeli\_32 firmware, which is designed for superior functionality and performance.
- Supports regular 1-2ms pulse width input, as well as Oneshot125 (125-250us), Oneshot42 (41.7-83.3us) and Multishot (5-25us). The input signal is automatically detected by the ESC upon power up.
- All Dshot signals are supported.
- Damped light does regenerative braking, causing very fast motor retardation, and inherently also does active freewheeling.
- Small size and light weight, support higher KV motor and more power load.
- The output of the modular BEC can supply power to the receiver, steering gear and other external devices, which makes the application of the ESC more extensive.
- Adjustable BEC output 5V / 3A or 12V / 2A, more flexible application.
- Aluminum heat sink effectively slow down the temperature rise (40A/50A). Supports the RGB tricolor setting (20A/30A) to make the flight more colorful.



\*All pictures are for reference only

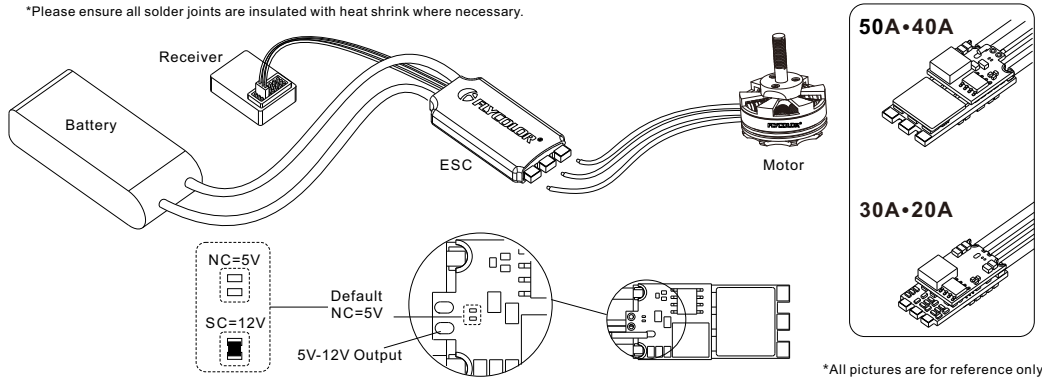
## 02 Specifications

Model	Con. Current (Good H.D.)	Burst Current (10S, Good H.D.)	BEC; LiPo	Weight (For reference)	Size (For reference)	LED
Francy-20A	20A	25A	5V/3A ; (3-6S) 12V/2A ; (4-6S)	12.5g	29x14x9mm	RGB LED
Francy-30A	30A	35A	5V/3A ; (3-6S) 12V/2A ; (4-6S)	12.5g	29x14x9mm	RGB LED
Francy-40A	40A	50A	5V/3A ; (3-6S) 12V/2A ; (4-6S)	16.5g	33x16x10mm	Red LED
Francy-50A	50A	60A	5V/3A ; (3-6S) 12V/2A ; (4-6S)	16.5g	33x16x10mm	Red LED

- 1) 40A/50A firmware: **Flycolor\_X\_Cross\_BL\_32**; 2) 20A/30A firmware: **Flycolor\_X\_Cross\_BL\_32\_35A**
- The supported working voltage is 3-6s liPo when 5V / 3A BEC is selected, it is 4-6s liPo when 12V / 2A BEC is selected.

## 03 Wiring diagram

\*Please ensure all solder joints are insulated with heat shrink where necessary.



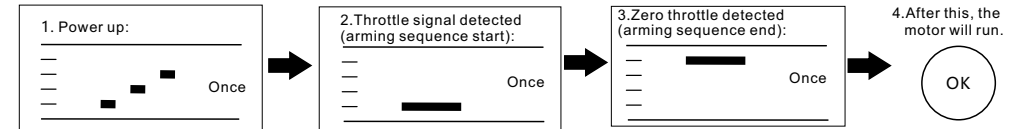
## 04 Programming parameter

Programming parameters below can be accessed from the configuration software (BLHeliSuite32):

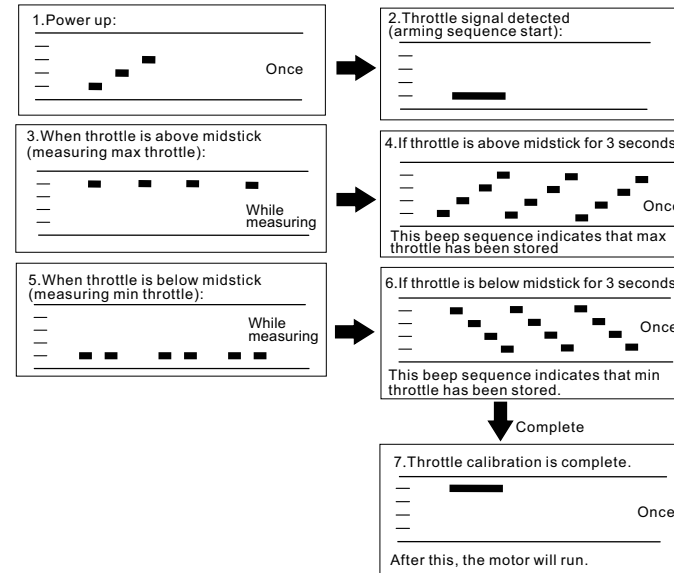
- Rampup power:** Rampup power can be set to relative values from 3% to 150%. This is the maximum power that is allowed when ramping up at low rpms and during startup. For low rpms, the maximum power to the motor is limited, in order to facilitate detection of low BEMF voltages. Rampup power also affects bidirectional operation, as the parameter is used to limit the power applied during direction reversal. During startup, the actual applied power depends on throttle input, and can be lower than the maximum level set by the rampup power parameter, but the minimum level is a quarter of the maximum level.
- Motor timing:** Motor timing can be set between approximately 1° and approximately 31° in approximately 1° increments (actual accurate values here are 15/16ths of a degree). Typically a medium setting will work fine, but if the motor stutters it can be beneficial to increase timing. Some motors with high inductance can have a very long commutation demagnetization time. This can result in motor stop or stutter upon quick throttle increase, particularly when running at a low rpm. Setting timing to high will allow more time for demagnetization, and often helps.
- PWM frequency:** Motor pwm frequency can be programmed between 16kHz and 48kHz. Higher pwm frequency can run motors smoother. Programmable frequency also allows for moving of small but potentially disturbing humps in the throttle response. All ESCs have these bumps, with BLHeli\_32 they can be moved in the rpm range, to a place where the system has low sensitivity to them.

- Demag compensation:** Demag compensation is a feature to protect from motor stalls caused by long winding demagnetization time after commutation. The typical symptom is motor stop or stutter upon quick throttle increase, particularly when running at a low rpm. As mentioned above, setting high commutation timing normally helps, but at the cost of efficiency. Generally, a higher value of the compensation parameter gives better protection. If demag compensation is set too high, maximum power can be somewhat reduced.
- Maximum Acceleration:** Maximum acceleration can be set between 0.1%/ms and 25.5%/ms. It can also be set to maximum, in which case acceleration is not limited. Limiting acceleration is primarily intended as a backup parameter that can be used in cases where too hard acceleration gives desyncs. When setting to e.g. 10%/ms, it means that the power applied to the motor is not allowed to increase by more than 10% per millisecond.
- Motor Direction:** Rotation direction can be set to Normal/Reversed/Bidirectional 3D/Bidirectional 3D Rev./Bidirectional Soft/Bidirectional Soft Rev. In bidirectional mode, center throttle is zero and above is fwd rotation and below is reverse rotation. When bidirectional operation is selected, throttle calibration is disabled.
- Startup Beep Volume:** Sets the strength of beeps under normal operation.
- Beacon/Signal Volume:** Sets the strength of beeps when beeping beacon beeps. The ESC will start beeping beacon beeps if the throttle signal has been zero for a given time. Note that setting a high beacon strength can cause hot motors or ESCs!
- Beacon delay:** Beacon delay sets the delay before beacon beeping starts.
- Throttle Cal Enable:** If disabled, throttle calibration is disabled.
- Min throttle, max throttle and center throttle:** These settings set the throttle range of the ESC. Center throttle is only used for bidirectional operation. The values given for these settings are for a normal 900us to 2100us input signal, and for the other input signals, the values must be scaled. For Dshot input signal, these settings have no effect.
- Thermal protection:** Thermal protection can be enabled or disabled. And the temperature threshold can be programmed. The programmable threshold is primarily meant as a support for hardware manufacturers to use, as different hardwares can have different tolerances on the max temperatures of the various components used.
- Low RPM power protect:** Power limiting for low RPMs can be enabled or disabled. Disabling it can be necessary in order to achieve full power on some low KV motors running on a low supply voltage. However, disabling it increases the risk of sync loss, with the possibility of toasting motor or ESC.
- Low Voltage Protection:** Low voltage protection can be set between 2.5V and 4.0V per lipo cell. Or it can be disabled. When enabled, it will limit power applied to the motor if the battery voltage drops below the programmed threshold. This feature is primarily intended for fixed wing crafts.
- Brake on stop:** Brake on stop can be set between 1% and 100%, or disabled. When not disabled, brake will be applied when throttle is zero. For nonzero throttle, this setting has no effect.
- LED Control:** LEDs can be controlled on ESCs that support it.
- Non Damped Mode:** OFF- Damped light is available; ON- No Damped light.
- Music Note Config:** Set up personalized music.
- Sine modulation mode:** Sine modulation mode can give a few percent more efficient running, as well as smoother running.
- Auto Telemetry:** When auto telemetry is enabled, the ESC will autonomously output telemetry at 32ms intervals, regardless of whether or not there are telemetry requests from the input signal.
- Stall Protection:** If the motor has attempted to start but not succeeded for a few seconds, it will stop attempting and wait for throttle to be zeroed before attempting again. Normal-protection is available, Relaxed- no protection.

## 05 Beeps-Normal operation



## 06 Beeps - Throttle calibration



1. Throttle calibration will be more simple if using Flight Controller Configurator.  
2. User need to calibrate the throttle range when starting to use a new ESC or another transmitter.  
3. When the input signal is Dshot, throttle calibration is disabled, and the throttle calibration values are ignored.

Example: